

# Free Probability based Capacity Calculation of Multiantenna Gaussian Fading Channels with Cochannel Interference

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## Abstract

During the last decade, it has been well understood that communication over multiple antennas can increase linearly the multiplexing capacity gain and provide large spectral efficiency improvements. However, the majority of studies in this area were carried out ignoring cochannel interference. Only a small number of investigations have considered cochannel interference, but even therein simple channel models were employed, assuming identically distributed fading coefficients. In this paper, a generic model for a multi-antenna channel is presented incorporating four impairments, namely additive white Gaussian noise, flat fading, path loss and cochannel interference. Both point-to-point and multiple-access MIMO channels are considered, including the case of cooperating Base Station clusters. The asymptotic capacity limit of this channel is calculated based on an asymptotic free probability approach which exploits the additive and multiplicative free convolution in the  $R$ - and  $S$ -transform domain respectively, as well as properties of the  $\eta$  and Stieltjes transform. Numerical results are utilized to verify the accuracy of the derived closed-form expressions and evaluate the effect of the cochannel interference.

## Index Terms

Information theory, Information Rates, Multiuser channels, MIMO systems, Cochannel Interference, Land mobile radio cellular systems, Eigenvalues and eigenfunctions.

## I. INTRODUCTION

In many cases, wireless communication systems have to operate in the interference-limited regime, where the cochannel interference is much more pronounced than the receiver noise. This applies to all modern cellular systems, as well as in multi-spot beam satellites, where frequency reuse is employed over spatially separated geographical areas. The capacity of those systems is interference-limited, since by increasing the transmit power both received signal and cochannel interference increase and eventually the Signal over Interference and Noise Ratio (SINR) saturates. Although a number of previous studies in the literature [1], [2], [3], [4], [5] have looked into the effect

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of cochannel interference, the majority of the employed channel models were focused on specific cases, failing to capture the wide range of affected systems.

In this context, this paper generalizes and studies the effect of cochannel interference on multiantenna Gaussian fading channels. More specifically, the main contributions herein are:

- 1) The introduction of a generic multidimensional channel model which encompasses four channel impairments, namely additive white Gaussian noise (AWGN), flat fading, path loss and cochannel interference. The proposed model can be employed as a generalization of point-to-point MIMO channels, as well as uplink and downlink channels of MIMO cellular systems, cooperating Base Station clusters and multi-spot beam satellite systems.
- 2) The analytical calculation of the asymptotic eigenvalue probability distribution function (a.e.p.d.f.) based on a free probability approach which exploits the additive and multiplicative free convolution [6] in the  $R$ - and  $S$ -transform domain respectively, as well as properties of the  $\eta$  and Stieltjes transform.
- 3) The derivation of closed-form methods which calculate the system capacity based on the number of dimensions and the transmit power of useful signals and cochannel interference.
- 4) Numerical results which verify the validity of the free probability derivations and provide insights into the capacity performance of cochannel-interfered systems.

The remainder of this paper is structured as follows: Section II introduces the generic channel model and provides a detailed review of cochannel interference scenarios. Section III describes the free probability derivations and the capacity results, while cumbersome mathematical derivations are postponed to the appendix. Section IV verifies the accuracy of the analysis by comparing with Monte Carlo simulations and evaluates the effect of the cochannel interference in the context of cooperating BS clusters. Section V concludes the paper.

#### A. Notation

Throughout the formulations of this paper,  $\mathbb{E}[\cdot]$  denotes the expectation,  $(\cdot)^H$  denotes the conjugate transpose matrix,  $(\cdot)^T$  denotes the transpose matrix,  $\odot$  denotes the Hadamard product and  $\otimes$  denotes the Kronecker product. The Frobenius norm of a matrix or vector is denoted by  $\|\cdot\|$ , the absolute value of a scalar is denoted by  $|\cdot|$  and the delta function is denoted by  $\delta(\cdot)$ .  $(\cdot)^+$  is equivalent to  $\max(0, \cdot)$  and  $1\{\cdot\}$  is the indicator function.

## II. GENERIC CHANNEL MODEL & RELATED WORK

#### A. Generic Channel Model

The generic channel model which combines additive white Gaussian noise, flat fading, path loss and cochannel interference can be expressed as follows:

$$\mathbf{y} = \mathbf{H}\mathbf{x} + \mathbf{H}_I\mathbf{x}_I + \mathbf{z}, \quad (1)$$

where  $\mathbf{y}$  denotes the  $K \times 1$  received symbol vector and the  $K \times 1$  vector  $\mathbf{z}$  denotes AWGN with  $\mathbb{E}[\mathbf{z}] = \mathbf{0}$  and  $\mathbb{E}[\mathbf{z}\mathbf{z}^H] = \mathbf{I}^1$ . The  $M \times 1$  vector  $\mathbf{x}$  denotes the transmitted symbol vector with Signal to Noise Ratio (SNR)  $\mu$

<sup>1</sup>The variance of AWGN has been normalized to 1 to simplify notations

$(\mathbb{E}[\mathbf{x}\mathbf{x}^H] = \mu\mathbf{I})$ , while the  $N \times 1$  vector  $\mathbf{x}_I$  denotes cochannel interference with Interference to Noise Ratio (INR)  $\nu$  ( $\mathbb{E}[\mathbf{x}_I\mathbf{x}_I^H] = \nu\mathbf{I}$ ). It should be noted that  $\mu$  represents the transmitted desired signal over noise power ratio (TSNR), while  $\nu$  represents the transmitted interference over noise power ratio (TINR). The  $K \times M$  channel matrix  $\mathbf{H} = \Sigma \odot \mathbf{G}$  comprises of the Hadamard product of a Gaussian matrix  $\text{vec}(\mathbf{G}) \sim \mathcal{CN}(\mathbf{0}, \mathbf{I})$  including the flat fading coefficients of the communication system and a variance profile matrix  $\Sigma$  including the path loss coefficients of the communication system. Similarly, the  $K \times N$  channel matrix  $\mathbf{H}_I = \Sigma_I \odot \mathbf{G}_I$  comprises of the Hadamard product of a Gaussian matrix  $\text{vec}(\mathbf{G}_I) \sim \mathcal{CN}(\mathbf{0}, \mathbf{I})$  including the flat fading coefficients of the cochannel interference and a variance profile matrix  $\Sigma_I$  including the path loss coefficients of the cochannel interference. The exact structure of the variance profile matrices depends on the considered wireless scenario and it is discussed in detail in the following section<sup>2</sup>. It is also assumed that:

- $\mathbf{x}$  and  $\mathbf{x}_I$  are Gaussian inputs
- Cochannel interference is treated as noise
- Channel State Information (CSI) is available at the receiver but not at the transmitters. Therefore, no input optimization takes place in order to avoid cochannel interference.

In the proposed model, the combined effect of receiver noise plus cochannel interference can be represented by a combined vector  $\mathbf{z}_I = \mathbf{H}_I\mathbf{x}_I + \mathbf{z}$  which is characterized as colored since its covariance  $\mathbb{E}[\mathbf{z}_I\mathbf{z}_I^H] = \mathbf{I} + \nu\mathbf{H}_I\mathbf{H}_I^H$  is no longer proportional to the identity matrix. The capacity of the generic model normalized by the number of receive dimensions is given by an expression of the following form<sup>3</sup> [8], [1], [2]:

$$C = \frac{1}{K}\mathbb{E} \left[ \log \det \left( \mathbf{I} + \mu\mathbf{H}\mathbf{H}^H (\mathbf{I} + \nu\mathbf{H}_I\mathbf{H}_I^H)^{-1} \right) \right]. \quad (2)$$

*Remark 2.1:* At this point, it should be noted that the variance profile matrices should satisfy a number of conditions for the analytical results of section III to be valid:

- $\Sigma$  and  $\Sigma_I$  are assumed to have uniformly bounded entries with growing dimensions and satisfy Lindeberg's condition.
- $\Sigma$  and  $\Sigma_I$  are assumed to be asymptotically row-regular.

*Definition 2.1:* An  $N \times K$  matrix  $\mathbf{X}$  is asymptotically row-regular [6] if

$$\lim_{K \rightarrow \infty} \frac{1}{K} \sum_{j=1}^K \mathbb{1} \{ X_{i,j} \leq \alpha \} \quad (3)$$

is independent of  $i$  for all  $\alpha \in \mathbb{R}$ , as the aspect ratio  $\frac{K}{N}$  converges to a constant.

<sup>2</sup>In the previous notation, it is assumed that TSNR is identical for all desired dimensions and the TINR for all interfering dimensions. If this is not the case, variations in the transmit power across the multiple dimensions can be incorporated in the variance profile matrices  $\Sigma$  and  $\Sigma_I$  respectively.

<sup>3</sup>It should be noted that eq. (2) can be also written as  $C = \frac{1}{K}\mathbb{E}[\log \det(\mathbf{I} + \mu\mathbf{H}\mathbf{H}^H + \nu\mathbf{H}_I\mathbf{H}_I^H)] - \frac{1}{K}\mathbb{E}[\log \det(\mathbf{I} + \nu\mathbf{H}_I\mathbf{H}_I^H)]$  as in [7]. However, this paper focuses on eq. (2) in order to distinguish and exploit the structure of matrices  $\Sigma$  and  $\Sigma_I$ .

To simplify the notations during the mathematical analysis, the following auxiliary variables are defined:

$$\begin{aligned}\mathbf{K} &= \mu \mathbf{H} \mathbf{H}^H (\mathbf{I} + \nu \mathbf{H}_I \mathbf{H}_I^H)^{-1} \\ \mathbf{M} &= (\mathbf{I} + \nu \mathbf{H}_I \mathbf{H}_I^H)^{-1} \\ \mathbf{N} &= \mu \mathbf{H} \mathbf{H}^H \\ \tilde{\mathbf{N}} &= \nu \mathbf{H}_I \mathbf{H}_I^H \\ \beta &= \frac{M}{K} \\ \gamma &= \frac{N}{K} \\ q &= \frac{\|\Sigma\|^2}{MK} \\ p &= \frac{\|\Sigma_I\|^2}{NK}\end{aligned}$$

where  $\beta, \gamma$  are the ratios of horizontal to vertical dimensions of matrix  $\mathbf{H}, \mathbf{H}_I$  respectively and  $q, p$  are the squared Frobenius norms of matrices  $\Sigma, \Sigma_I$  respectively normalized by the matrix size.

### B. Wireless Scenarios with Cochannel Interference

This generic model can encompass a wide range of point-to-point and multiple-access MIMO channels by altering the structure of the variance profile matrices and the meaning of the channel matrix dimensions, as described in the following paragraphs.

1) *Single MIMO Link with Equidistant Cochannel Interference*: In this scenario, a single MIMO link is considered whereas the receiver is impaired by a) a single cochannel MIMO interferer or b) a number of equidistant interferers. An example for case (a) would be two point-to-point MIMO links operating in close proximity, while for case (b) a cell-edge multiple-antenna terminal at the downlink channel receiving interference from adjacent equidistant Base Stations (BSs). In the described scenarios, the path loss coefficients can be considered identical and therefore the variance profile matrices are matrices of ones:  $\Sigma = \Sigma_I = \mathbb{I}$ . In addition,  $K$  and  $M$  equal the number of receive antennas and the number of transmit antennas at the desired terminal respectively.  $N$  equals the number of transmit antennas at the interfering terminal in case (a) or the number of interfering BSs in case (b). Authors in [3] investigated the correlated MIMO capacity with correlated cochannel interference, as well as the optimum signaling for fading channels. Using complex integrals and Grassman variables, the mutual information moments have been derived and a method for optimizing the input signal covariance based on the correlation matrices was presented. It has been shown that in many cases, the input optimization yields capacities close to the closed-loop capacity, where instantaneous channel state information is available at the receiver.

2) *Single MIMO Link with Distributed Cochannel Interference*: In this scenario, a MIMO link operating within a traditional cellular system is assumed. In the uplink, each BS receives cochannel interfering signals from the User Terminals (UTs) of adjacent cells. Similarly, in the downlink each UT receives cochannel interference from adjacent BSs. The main differentiation between uplink and downlink is that in the former case interference originates from

a large number of low-power randomly-distributed sources (UTs), whereas in the latter case interference originated from a small number of high-power regularly-distributed sources (BSs). In both uplink and downlink, the variance profile matrix  $\Sigma$  is a matrix of ones  $\Sigma = \mathbb{I}$ , while the structure of matrix  $\Sigma_I = \sigma_I^T \otimes \mathbb{I}$  is dictated by the spatial distribution of the interferers, where  $\sigma_I$  is a vector including the path loss components of the interferers. Regarding the uplink channel matrix dimensions,  $K$  and  $M$  refer to the number of receive antennas at the BS and the number of transmit antennas at the UT respectively, while  $N$  refers to the number of interfering UTs multiplied by the number of transmit antennas per UT. Authors in [2] have investigated this scenario and have derived an asymptotic closed-form expression as a function of  $K, M, N, p, q$  for AWGN and fading channels. According to this study the spatial noise coloring due to cochannel interference can be exploited by the multiple-antenna receiver in order to achieve higher channel capacities. Subsequently, the author in [1] has studied the optimum signaling in MIMO channels with cochannel interference. In this context, it has been found that the optimal signaling converges to the interference-free signaling only when interference is sufficiently weak or sufficiently strong.

3) *MIMO Cellular System with Wideband Transmission Scheme*: This scenario considers a single cell which operates on wideband transmission scheme (i.e. superposition coding) and receives interference from adjacent cells. The wideband transmission scheme implies that all UTs of the cell of interest transmit over the same channel dimensions using superposition coding [9], [10]. Assuming BS and UTs equipped with multiple antennas, the uplink can be represented by a MIMO multiple-access channel. In this case, the structure of matrix  $\Sigma = \sigma^T \otimes \mathbb{I}$  is dictated by the spatial distribution of the intra-cell UTs, while  $\Sigma_I = \sigma_I^T \otimes \mathbb{I}$  is dictated by the inter-cell interferers, where  $\sigma$  is a vector including the path loss components of the desired UTs. Regarding the channel matrix dimensions,  $K$  refers to the number of receive antennas at the BS,  $M$  refers to the number of UTs times the number of transmit antennas at the UT and  $N$  refers to the number of interfering UTs times the number of transmit antennas per UT. This scenario has been studied in [11], where various multiuser MIMO processing techniques are considered in the presence of cochannel interference. Furthermore, it is shown therein that linear MMSE (Minimum Mean Square Error) filtering yields eq. (2), assuming full CSI at the receiver.

4) *Cooperating BS Cluster*: In this scenario, a cluster of cooperating BSs (or distributed antennas) is considered, receiving interference from similar adjacent clusters. Many variations of this scenario can be described by the generic channel model. For example, the BSs and UTs may be equipped with single or multiple antennas. In addition, orthogonal (single transmitting UT per cluster) or wideband (multiple transmitting UTs per cluster) transmission scheme can be considered. In all aforementioned cases the variance profile matrices have a special structure defined by the spatial distribution of BS clusters and intra-cell/inter-cell UTs. The defining characteristic of all the aforementioned cases is that matrices  $\Sigma$  and  $\Sigma_I$  can no longer be expressed in terms of the vector  $\sigma$  or  $\sigma_I$ . The reader is referred to [12] for a detailed review of variance profile matrices for BS cooperation systems. Cooperating BS clusters were also considered in [4], using inter-cell scheduling to avoid cochannel interference. Furthermore, the authors in [5] consider BS clusters with frequency reuse 1 on a circular Wyner array, although all intra-cell UTs are assumed to have equal path loss coefficients in order to provide mathematical tractability.

*Remark 2.2:* It should be noted that the generic model and capacity derivation in this paper generalize all the

aforementioned scenarios by making no simplifying assumptions except the asymptotic row-regularity of the variance profile matrices. In terms of wireless scenarios, asymptotic row-regularity means that each receiving element collects in total the same power from all transmitters. This is always true for multiple collocated omnidirectional receive antennas, such as scenarios II-B1, II-B2. However, for spatially distributed receive antennas such as in scenarios II-B3, II-B4 asymptotic row-regularity translates into symmetric cells in terms of spatial user distributions. This assumption becomes more valid for asymptotically large number of cells and users.

### III. EIGENVALUE DISTRIBUTION ANALYSIS

As it can be seen, the generic channel model of eq. (1) and its ergodic capacity in eq. (2) describe a wide range of multiantenna and multiple-access channels impaired by additive white Gaussian noise, flat fading, path loss and cochannel interference. In order to tackle this problem analytically, we resort to asymptotic analysis which entails that the dimensions of the channel matrices grow to infinity assuming proper normalizations. It has already been shown in many occasions that asymptotic analysis yields results which are also valid for finite dimensions [6], [2], [13]. In other words, the capacity expression converges quickly to a deterministic value as the number of channel matrix dimensions increases. Eq. (2) can be written asymptotically as:

$$\begin{aligned} C &= \lim_{K,M,N \rightarrow \infty} \frac{1}{K} \mathbb{E} \left[ \log \det \left( \mathbf{I} + \mu \mathbf{H} \mathbf{H}^H \left( \mathbf{I} + \nu \mathbf{H}_I \mathbf{H}_I^H \right)^{-1} \right) \right] \\ &= \lim_{K,M,N \rightarrow \infty} \mathbb{E} \left[ \frac{1}{K} \sum_{i=1}^K \log (1 + \lambda_i(\mathbf{K})) \right] \\ &= \int_0^\infty \log (1 + x) f_{\mathbf{K}}^\infty(x) dx, \end{aligned} \quad (4)$$

where  $\lambda_i(\mathbf{K})$  is the  $i$ th eigenvalue of matrix  $\mathbf{K}$  and  $f_{\mathbf{K}}^\infty$  is the a.e.p.d.f. of  $\mathbf{K}$ . It should be noted that while the channel dimensions  $K, M, N$  grow to infinity the ratios of horizontal to vertical dimensions  $\beta, \gamma$  are kept constant. More importantly, TSNR and TINR  $\mu, \nu$  grow small as the transmit dimensions  $M, N$  grow large in order to guarantee that the system TSNR and TINR  $\tilde{\mu} = M\mu, \tilde{\nu} = N\nu$  remain constant and do not grow infinite in the context of asymptotic analysis. Based on the aforementioned conventions, the following auxiliary variables are defined:

$$\begin{aligned} \tilde{q} &= \frac{\tilde{\mu}q}{\beta} = K\mu q \\ \tilde{p} &= \frac{\tilde{\nu}p}{\gamma} = K\nu p \end{aligned}$$

To calculate the expression of eq. (4), it suffices to derive the a.e.p.d.f. of  $\mathbf{K}$ , which can be achieved through the principles of free probability theory [14], [15], [16], [17] as described in the following paragraphs.

*Remark 3.1:* It should be noted that other techniques have been also used in recent literature for large random matrix analysis. Most notably, the replica analysis method [18] and the deterministic equivalents method [19] have been applied in a range of wireless scenarios for deriving ergodic, outage capacities and precoding methods.

### A. Random Matrix Theory Preliminaries

Let  $f_{\mathbf{X}}(x)$  be the eigenvalue probability distribution function of a matrix  $\mathbf{X}$ .

*Definition 3.1:* The  $\eta$ -transform of a positive semidefinite matrix  $\mathbf{X}$  is defined as

$$\eta_{\mathbf{X}}(\gamma) = \int_0^\infty \frac{1}{1 + \gamma x} f_{\mathbf{X}}(x) dx. \quad (5)$$

*Definition 3.2:* The  $\Sigma$ -transform of a positive semidefinite matrix  $\mathbf{X}$  is defined as

$$\Sigma_{\mathbf{X}}(x) = -\frac{x+1}{x} \eta_{\mathbf{X}}^{-1}(x+1). \quad (6)$$

*Property 3.1:* The Stieltjes-transform of a positive semidefinite matrix  $\mathbf{X}$  can be derived by its  $\eta$ -transform using [6, Equation 2.48]

$$\mathcal{S}_{\mathbf{X}}(x) = -\frac{\eta_{\mathbf{X}}(-1/x)}{x}. \quad (7)$$

### B. Free Probability Results

The asymptotic capacity limit of this channel is calculated based on an asymptotic free probability approach which exploits the additive and multiplicative free convolution in the  $R$ - and  $\Sigma$ -transform domain respectively, as well as properties of the  $\eta$  and Stieltjes transform. The derivation methodology in this paper can be summarized as follows:

- 1) Derivation of a.e.p.d.f. of  $\mathbf{N}, \tilde{\mathbf{N}}$  through additive free convolution (Theorem 3.1)
- 2) Derivation of inverse  $\eta$ -transform of  $\mathbf{M}$  through Cauchy integration (Theorem 3.2)
- 3) Derivation of Stieltjes transform of  $\mathbf{K}$  through multiplicative free convolution in the  $S$ -transform domain (Theorem 3.3)
- 4) Calculation of  $f_{\mathbf{K}}^\infty$  through Lemma 3.2
- 5) Integration based on eq. (4) in order to calculate capacity

*Theorem 3.1:* The a.e.p.d.f. of  $\mathbf{N}, \tilde{\mathbf{N}}$  follows a scaled version of the Marčenko-Pastur law, as long as  $\Sigma, \Sigma_I$  are asymptotically row-regular.

*Proof:* Considering a Gaussian channel matrix  $\mathbf{G} \sim \mathcal{CN}(\mathbf{0}, \mathbf{I})$ , the empirical eigenvalue distribution of  $\frac{1}{K} \mathbf{G} \mathbf{G}^H$  converges almost surely (a.s.) to the non-random limiting eigenvalue distribution of the Marčenko-Pastur law [20], whose density function is given by

$$f_{\frac{1}{K} \mathbf{G} \mathbf{G}^H}^\infty(x) \xrightarrow{a.s.} f_{\text{MP}}(x, \beta) \quad (8)$$

$$f_{\text{MP}}(x, \beta) = (1 - \beta)^+ \delta(x) + \frac{\sqrt{(x - a)^+ (b - x)^+}}{2\pi x}$$

where  $a = (1 - \sqrt{\beta})^2$ ,  $b = (1 + \sqrt{\beta})^2$  and  $\eta$ -transform,  $S$ -transform are given by [6]

$$\eta_{\text{MP}}(x, \beta) = 1 - \frac{\phi(x, \beta)}{4x} \quad (9)$$

$$\begin{aligned} \phi(x, \beta) &= \left( \sqrt{x \left( 1 + \sqrt{\beta} \right)^2 + 1} - \sqrt{x \left( 1 - \sqrt{\beta} \right)^2 + 1} \right)^2 \\ \Sigma_{\text{MP}}(x, \beta) &= \frac{1}{\beta + x} \end{aligned} \quad (10)$$

and  $\beta$  is the ratio of the horizontal to the vertical dimension of the  $\mathbf{G}$  matrix.

According to [21], [22], [23], the channel covariance matrix  $\mathbf{H}\mathbf{H}^H$  can be decomposed into a sum of unit rank matrices which are assumed asymptotic free<sup>4</sup>. Using additive free convolution in the  $R$ -transform domain, the empirical eigenvalue distribution of  $\frac{1}{K}\mathbf{H}\mathbf{H}^H$  is shown to converge almost surely (a.s.) to a scaled version of the Marčenko-Pastur law [20], as long as  $\Sigma$  is asymptotically row-regular

$$f_{\frac{1}{K}\mathbf{H}\mathbf{H}^H}^\infty(x) \xrightarrow{a.s.} f_{\text{MP}}(qx, \beta) \quad (11)$$

or equivalently

$$f_{\mathbf{N}}^\infty(x) \xrightarrow{a.s.} f_{\text{MP}}(\tilde{q}x, \beta) \quad (12)$$

$$f_{\tilde{\mathbf{N}}}^\infty(x) \xrightarrow{a.s.} f_{\text{MP}}(\tilde{p}x, \gamma). \quad (13)$$

■

*Lemma 3.1:* The  $S$ -transform of  $\mathbf{N}, \tilde{\mathbf{N}}$  converges almost surely (a.s.) to:

$$\Sigma_{\mathbf{N}}(x) \xrightarrow{a.s.} \frac{1}{\tilde{q}} \frac{1}{\beta + x} \quad (14)$$

$$\Sigma_{\tilde{\mathbf{N}}}(x) \xrightarrow{a.s.} \frac{1}{\tilde{p}} \frac{1}{\gamma + x} \quad (15)$$

*Proof:* According to Theorem 3.1 and Definition 3.1,

$$\eta_{\mathbf{N}}(x) \xrightarrow{a.s.} \eta_{\text{MP}}(\tilde{q}x, \beta) \quad (16)$$

$$\eta_{\mathbf{N}}^{-1}(\tilde{q}x) \xrightarrow{a.s.} \frac{1}{\tilde{q}} \eta_{\text{MP}}^{-1}(x, \beta) \quad (17)$$

Using Definition 3.2 and eq. (9),

$$\begin{aligned} \Sigma_{\mathbf{N}}(x) &= -\frac{x+1}{x} \eta_{\mathbf{N}}^{-1}(x+1) \\ &\xrightarrow{a.s.} \frac{1}{\tilde{q}} \Sigma_{\text{MP}}(x, \beta) \\ &= \frac{1}{\tilde{q}} \frac{1}{\beta + x}. \end{aligned} \quad (18)$$

A similar derivation can be followed for  $\Sigma_{\tilde{\mathbf{N}}}(\nu)$ .

■

<sup>4</sup>The reader is referred to [21], [22] for a complete proof of Theorem 3.1.

*Theorem 3.2:* The inverse  $\eta$ -transform of  $\mathbf{M}$  is given by:

$$\eta_{\mathbf{M}}^{-1}(x) = -\frac{(x-1) \left( \sqrt{1 + (x-\gamma)^2 \tilde{p}^2 + (2\gamma+2x)\tilde{p}} + 1 + (\gamma-x)\tilde{p} \right)}{2x}. \quad (19)$$

*Proof:* See Appendix A. ■

*Theorem 3.3:* The inverse  $\eta$ -transform of  $\mathbf{K}$  is given by:

$$\eta_{\mathbf{K}}^{-1}(x) = \frac{1}{\tilde{q}} \frac{1}{\beta+x-1} \eta_{\mathbf{M}}^{-1}(x) \quad (20)$$

*Proof:* Assuming asymptotic freeness<sup>5</sup> between matrices  $\mathbf{N}$  and  $\mathbf{M}$ , the  $\Sigma$ -transform of  $\mathbf{K}$  is given by multiplicative free convolution:

$$\begin{aligned} \Sigma_{\mathbf{K}}(x) &= \Sigma_{\mathbf{N}}(x) \Sigma_{\mathbf{M}}(x) \xleftrightarrow{(a)} \\ \left(-\frac{x+1}{x}\right) \eta_{\mathbf{K}}^{-1}(x+1) &= \frac{1}{\tilde{q}} \frac{1}{\beta+x} \left(-\frac{x+1}{x}\right) \eta_{\mathbf{M}}^{-1}(x+1) \end{aligned}$$

where step (a) combines Definition 3.2 and eq. (14). The variable substitution  $y = x+1$  yields eq. (20). ■

*Lemma 3.2:* The a.e.p.d.f. of  $\mathbf{K}$  is obtained by determining the imaginary part of the Stieltjes transform  $\mathcal{S}$  for real arguments

$$f_{\mathbf{K}}^\infty(x) = \lim_{y \rightarrow 0^+} \frac{1}{\pi} \Im \{ \mathcal{S}_{\mathbf{K}}(x+jy) \}, \quad (21)$$

where the Stieltjes-transform  $\mathcal{S}$  of  $\mathbf{K}$  is given by Property 3.1 and the  $\eta$ -transform of  $\mathbf{K}$  is calculated by inverting eq. (20).

*Lemma 3.3:* The a.e.p.d.f. of  $\mathbf{M}$  is obtained by determining the imaginary part of the Stieltjes transform  $\mathcal{S}$  for real arguments, where the Stieltjes-transform  $\mathcal{S}$  of  $\mathbf{M}$  is given by Property 3.1 and the  $\eta$ -transform of  $\mathbf{M}$  is given by eq. (27) in Appendix A.

#### IV. NUMERICAL RESULTS

In order to verify the accuracy of the derived closed-form expressions and gain some insights on the capacity performance of the proposed generic model, a number of numerical results are presented in this section. In the following figures, solid lines are plotted based on closed-form expressions, while bars and circle points are calculated based on Monte Carlo simulations.

<sup>5</sup>Independent unitarily invariant matrices with compactly supported asymptotic spectra [6, Example 2.45], such as Wishart and inverse Wishart matrices with identity covariance matrix [24], are asymptotically free. The matrices  $\mathbf{N}$  and  $\mathbf{M}$  are independent, but the unitary invariance is not straightforward. More specifically,  $\mathbf{N}$  is a Wishart matrix with a covariance matrix which depends on  $\Sigma$  and thus its distribution belongs to a more general class, called elliptically contoured matrix distribution [24]. In addition,  $\mathbf{M}$  is the inverse of a non-central Wishart matrix as the sum of the channel covariance and the identity matrix. Nevertheless, the assumption of asymptotic freeness has been motivated by the accuracy of eigenvalue distributions and the fact that similar approximations have been already investigated in an information theoretic context, providing useful analytical insights and accurate numerical results [25], [26].

### A. A.e.p.d.f. Results

The accuracy of the derived closed-form expressions for matrices  $\mathbf{K}, \mathbf{M}, \mathbf{N}$  is depicted in Figure 1. The solid line in subfigure 1(a) is drawn using Theorem 3.1 and specifically eq. (12), in subfigure 1(b) using Lemma 3.3 and in subfigure 1(c) Lemma 3.2. The histograms denote the p.d.f. of matrices  $\mathbf{K}, \mathbf{M}, \mathbf{N}$  calculated numerically based on Monte Carlo simulations. More specifically, the matrices  $\mathbf{G}$  and  $\mathbf{G}_I$  are generated using independent identically distributed (i.i.d.) complex circularly symmetric (c.c.s.) elements for  $10^3$  fading instances and the matrices  $\Sigma$  and  $\Sigma_I$  using the following simplified model for diminishing off-diagonals:

$$\sigma_{i,j} = \frac{1}{\sqrt{1 + |i - j|}}, \quad (22)$$

where  $\sigma_{i,j}$  is the  $(i, j)$ th matrix element of  $\Sigma$  or  $\Sigma_I$ . It can be seen that there is a perfect agreement between the two sets of results.

Figure 2 depicts the effect of transmit power  $(\mu, \nu)$  and channel dimensions  $(\beta, \gamma)$  on the a.e.p.d.f. of matrix  $\mathbf{K}$ . As it can be observed, the a.e.p.d.f. has four degrees of freedom, each one contributing to the shape of the curve. The final shape would be determined by combining those four contributions, namely the transmit power of desired dimensions  $\mu$ , the transmit power of interfering dimensions  $\nu$ , desired transmit over receive dimensions  $\beta$  and interfering transmit over receive dimensions  $\gamma$ . The effect of the quantities  $q, p$  is similar to that of  $\mu, \nu$  and it is not depicted for the sake of conciseness.

### B. Capacity Results

In this paragraph, the focus is on cooperating BS clusters in the context of a linear cellular array with single-antenna BSs / UTs and wideband transmission scheme, as depicted in Figure 3. However, the presented closed-form expressions can be straightforwardly applied to planar arrays and multiple-antenna BSs and UTs. The parameters used for producing the capacity results are presented in Table I. The transmit power  $P_T$ , the number of UTs per cell  $\beta$  and the cell size  $R$  are kept constant while the number of cells  $K$  participating in the cluster varies. The simulated system considers 50 cells in total and  $10^3$  Monte Carlo (MC) iterations. The UTs are assumed to be distributed on a regular grid across the system coverage span. TSNR and TINR are calculated as follows:

$$\mu = \nu = \frac{P_T}{N_0 B}, \quad (23)$$

while a power-law path loss model [27], [28], [12] is employed for constructing the variance profile matrices  $\Sigma, \Sigma_I$ :

$$\sigma_{i,j} = \sqrt{P_0} \left( 1 + \frac{d_{i,j}}{d_0} \right)^{-\frac{n}{2}}, \quad (24)$$

where  $\sigma_{i,j}$  is the  $(i, j)$ th matrix element and  $d_{i,j}$  is the spatial distance between the  $i$ th receive dimension and the  $j$ th transmit dimension. The quantities  $q, p$  can be calculated either numerically or based on closed-form expressions as described in [29], [30] for linear and planar cellular arrays respectively. It should also be noted that scaling the cluster size  $K$  affects the structure of matrices  $\Sigma, \Sigma_I$  and as a result the quantities  $q, p$ . In this direction, the capacity plot versus cluster size in Figure 4 includes two sets of results. The circle points denote values calculated based on

simulating the channel matrices and averaging using eq. (2). The solid line is plotted using eq. (4) and Theorem 3.2. As it can be seen, the potential spectral efficiency of cooperating BS clusters is very high even for moderate cluster sizes.

## V. CONCLUSION

In this paper, a generic multiantenna channel model was introduced, incorporating Gaussian noise, flat fading, path loss and cochannel interference. The proposed model generalizes and extends previous models in the literature by considering profile matrices which shape the variance of the fading coefficients for both desired and interfering signal dimensions. As a result, it is possible to describe a wide range of cochannel interference scenarios, including single-user and multi-user MIMO, as well as cooperating BS clusters, also known as distributed antenna systems. Based on a free probability approach, the asymptotic eigenvalue distribution has been derived, resulting in closed-form expressions which depend on TSNR, TINR, channel dimensions and norms of the variance profile matrices. Furthermore, the derivations herein have demonstrated how complicated channel matrix expressions can be tackled by additive and multiplicative free convolution in the  $R$ - and  $S$ -transform domain respectively, as well as properties of the  $\eta$  and Stieltjes transform. Finally, the derived a.e.p.d.f. of the matrix products in the log det formula was utilized to calculate the capacity of cooperating BS clusters by varying the size of the cluster and to provide an estimation of the resulting spectral efficiencies.

## APPENDIX A

### PROOF OF THEOREM 3.2

Since the a.e.p.d.f.  $f_{\tilde{\mathbf{N}}}^\infty(x)$  is known, the a.e.p.d.f. of  $f_{\mathbf{M}}^\infty(y)$  can be calculated considering that  $y = (1 + x)^{-1}$ , where  $y$  and  $x$  represent the eigenvalues of  $\mathbf{M}$  and  $\tilde{\mathbf{N}}$  respectively:

$$\begin{aligned} f_{\mathbf{M}}^\infty(y(x)) &= \left| \frac{1}{y'(y^{-1}(x))} \right| \cdot f_{\tilde{\mathbf{N}}}^\infty(y^{-1}(x)) \\ &= x^{-2} f_{\tilde{\mathbf{N}}}^\infty\left(\frac{1-x}{x}\right). \end{aligned} \quad (25)$$

Following the definition of  $\eta$ -transform [6, Definition 2.11],[31]:

$$\begin{aligned}
\eta_{\mathbf{M}}(\psi) &= \int_{-\infty}^{+\infty} \frac{1}{1 + \psi x} f_{\mathbf{M}}^{\infty}(x) dx \\
&= \int_{-\infty}^{+\infty} \frac{1}{1 + \psi x} \frac{1}{x^2} f_{\tilde{\mathbf{N}}} \left( \frac{1-x}{x} \right) dx \\
&\stackrel{(a)}{=} - \int_{+\infty}^{-\infty} \frac{w+1}{1+\psi+w} f_{\tilde{\mathbf{N}}}(w) dw \\
&= \int_{-\infty}^{+\infty} \frac{w+1}{1+\psi+w} f_{\tilde{\mathbf{N}}}(w) dw \\
&= \int_{\tilde{a}}^{\tilde{b}} \frac{w+1}{1+\psi+w} \frac{1}{2\pi w \tilde{p}} \sqrt{(b-w)(x-w)} dw \\
&\stackrel{(b)}{=} -\gamma \int_0^\pi \frac{2}{\pi} \frac{1 + \tilde{p}(1 + \gamma + 2\sqrt{\gamma} \cos \omega)}{(1 + \gamma + 2\sqrt{\gamma} \cos \omega)(1 + \psi + \tilde{p}(1 + \gamma + 2\sqrt{\gamma} \cos \omega))} \sin^2 \omega d\omega \\
&= -\gamma \frac{1}{\pi} \int_0^{2\pi} \frac{(1 + \tilde{p}(1 + \gamma + \sqrt{\gamma}(e^{i\omega} + e^{-i\omega})))((e^{i\omega} - e^{-i\omega})/2i)^2}{(1 + \gamma + \sqrt{\gamma}(e^{i\omega} + e^{-i\omega}))(1 + \psi + \tilde{p}(1 + \gamma + \sqrt{\gamma}(e^{i\omega} + e^{-i\omega})))} d\omega \\
&\stackrel{(c)}{=} \gamma \frac{1}{4i\pi} \oint_{|\zeta|=1} \frac{(1 + \tilde{p}(1 + \gamma + \sqrt{\gamma}(\zeta + \zeta^{-1}))) (\zeta - \zeta^{-1})^2}{\zeta(1 + \gamma + \sqrt{\gamma}(\zeta + \zeta^{-1}))(1 + \psi + \tilde{p}(1 + \gamma + \sqrt{\gamma}(\zeta + \zeta^{-1})))} d\zeta \\
&= \gamma \frac{1}{4i\pi} \oint_{|\zeta|=1} \frac{((1 + \tilde{p}(1 + \gamma))\zeta + \sqrt{\gamma}\tilde{p}(\zeta^2 + 1))(\zeta^2 - 1)^2}{\zeta^2((1 + \gamma)\zeta + \sqrt{\gamma}(\zeta^2 + 1))(\zeta(1 + \psi + \tilde{p}(1 + \gamma)) + \sqrt{\gamma}\tilde{p}(\zeta^2 + 1))} d\zeta \quad (26)
\end{aligned}$$

where  $\tilde{a} = \tilde{p}(1 - \sqrt{\gamma})^2$  and  $\tilde{b} = \tilde{p}(1 + \sqrt{\gamma})^2$ . Step (a) requires the variable substitution  $x = 1/(w+1)$ ,  $dx = -1/(1+w)^2 dw$ , step (b) requires  $w = 1 + \gamma + 2\sqrt{\gamma} \cos \omega$ ,  $dw = 2\sqrt{\gamma}(-\sin \omega) d\omega$  and step (c)  $\zeta = e^{i\omega}$ ,  $d\zeta = i\zeta d\omega$ .

Subsequently, a Cauchy integration is performed by calculating the poles  $\zeta_i$  and residues  $\rho_i$  of eq. (26):

$$\begin{aligned}
\zeta_0, 1 &= 0, \\
\zeta_{2,3} &= \frac{-(1 + \gamma) \pm (1 - \gamma)}{2\sqrt{\gamma}}, \\
\zeta_{4,5} &= \frac{-(1 + \gamma)\tilde{p} - 1 - \psi \pm \sqrt{(\gamma - 1)^2 \tilde{p}^2 + 2(1 + \psi)(1 + \gamma)\tilde{p} + (1 + \psi)^2}}{2\tilde{p}\sqrt{\gamma}}, \\
\rho_0 &= -\frac{\tilde{p} + \tilde{p}\gamma + \psi}{\tilde{p}\gamma}, \\
\rho_1 &= \frac{1}{\sqrt{\gamma}}, \\
\rho_{2,3} &= \pm \frac{\gamma - 1}{\gamma + \psi\gamma}, \\
\rho_{4,5} &= \pm \frac{(-(1 + \gamma)\tilde{p} + 1 + \psi)\sqrt{(\gamma - 1)^2 \tilde{p}^2 + 2(1 + \psi)(1 + \gamma)\tilde{p} + (1 + \psi)^2} + (\gamma - 1)^2 \tilde{p}^2 + 2(1 + \psi)(1 + \gamma)\tilde{p} + (1 + \psi)^2}{\tilde{p}\gamma(1 + \psi)(-\sqrt{(\gamma - 1)^2 \tilde{p}^2 + 2(1 + \psi)(1 + \gamma)\tilde{p} + (1 + \psi)^2} + (1 + \gamma)\tilde{p} + 1 + \psi)} \psi
\end{aligned}$$

Using the residues which are located within the unit disk, the Cauchy integration yields:

$$\begin{aligned}
\eta_{\mathbf{M}}(\psi) &= -\frac{\gamma}{2}(\rho_0 + \rho_2 + \rho_5) \\
&= \frac{-(\psi^2 + (1 + (1 + \gamma)\tilde{p})\psi + \tilde{p})\sqrt{\tilde{p}^2(-1 + \gamma)^2 + 2(1 + \psi)(\gamma + 1)\tilde{p} + (1 + \psi)^2} + \psi^3 + (2 + (2 + 2\gamma)\tilde{p})\psi^2 + (1 + (1 + \gamma^2)\tilde{p}^2 + (2\gamma + 3)\tilde{p})\psi + (\gamma + 1)\tilde{p}^2 + \tilde{p}}{(1 + \psi)(-\sqrt{\tilde{p}^2(-1 + \gamma)^2 + 2(1 + \psi)(\gamma + 1)\tilde{p} + (1 + \psi)^2} + \psi + 1 + (\gamma + 1)\tilde{p})} \quad (27)
\end{aligned}$$

Inversion yields eq. (19).

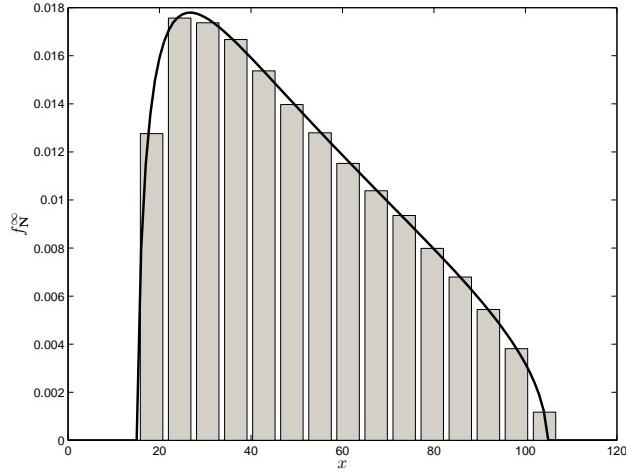
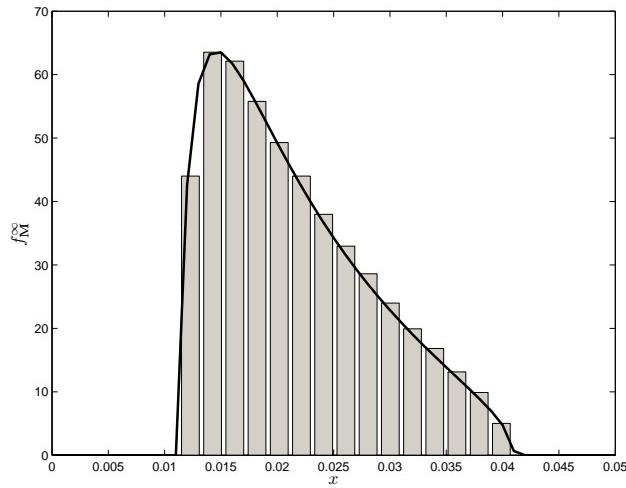
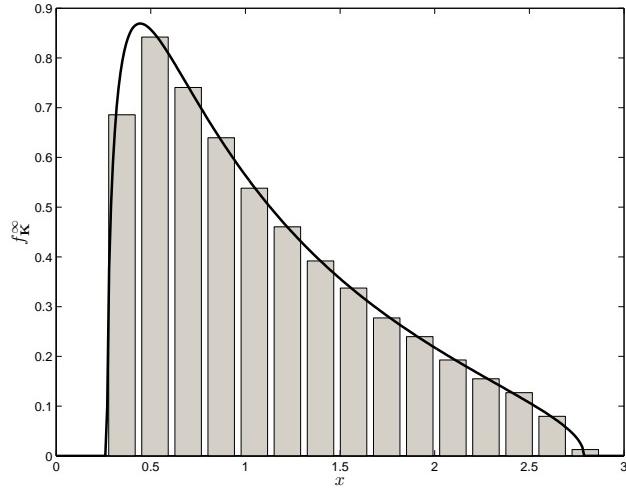
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TABLE I  
PARAMETERS FOR CAPACITY RESULTS

Parameter	Symbol	Value/Range (units)
Cell Radius	$R$	1 Km
Reference Distance	$d_0$	1 m
Reference Path Loss	$P_0$	34.5 dB
Path Loss Exponent	$n$	3.5
UTs per Cell	$\beta$	10
Cluster Size	$K$	1 – 10
Total number of cells	$K + \frac{N}{\beta}$	50
UT Transmit Power	$P_T$	200 mW
Thermal Noise Density	$N_0$	-169 dBm/Hz
Channel Bandwidth	$B$	5 MHz
Number of MC iterations		$10^3$

(a) A.e.p.d.f. for matrix  $\mathbf{N}$ (b) A.e.p.d.f. for matrix  $\mathbf{M}$ (c) A.e.p.d.f. for matrix  $\mathbf{K}$ Fig. 1. A.e.p.d.f. plots of matrices  $\mathbf{K}, \mathbf{M}, \mathbf{N}$ . Parameters:  $\beta = 5, \gamma = 10, \nu q = 10, \mu p = 5$ .

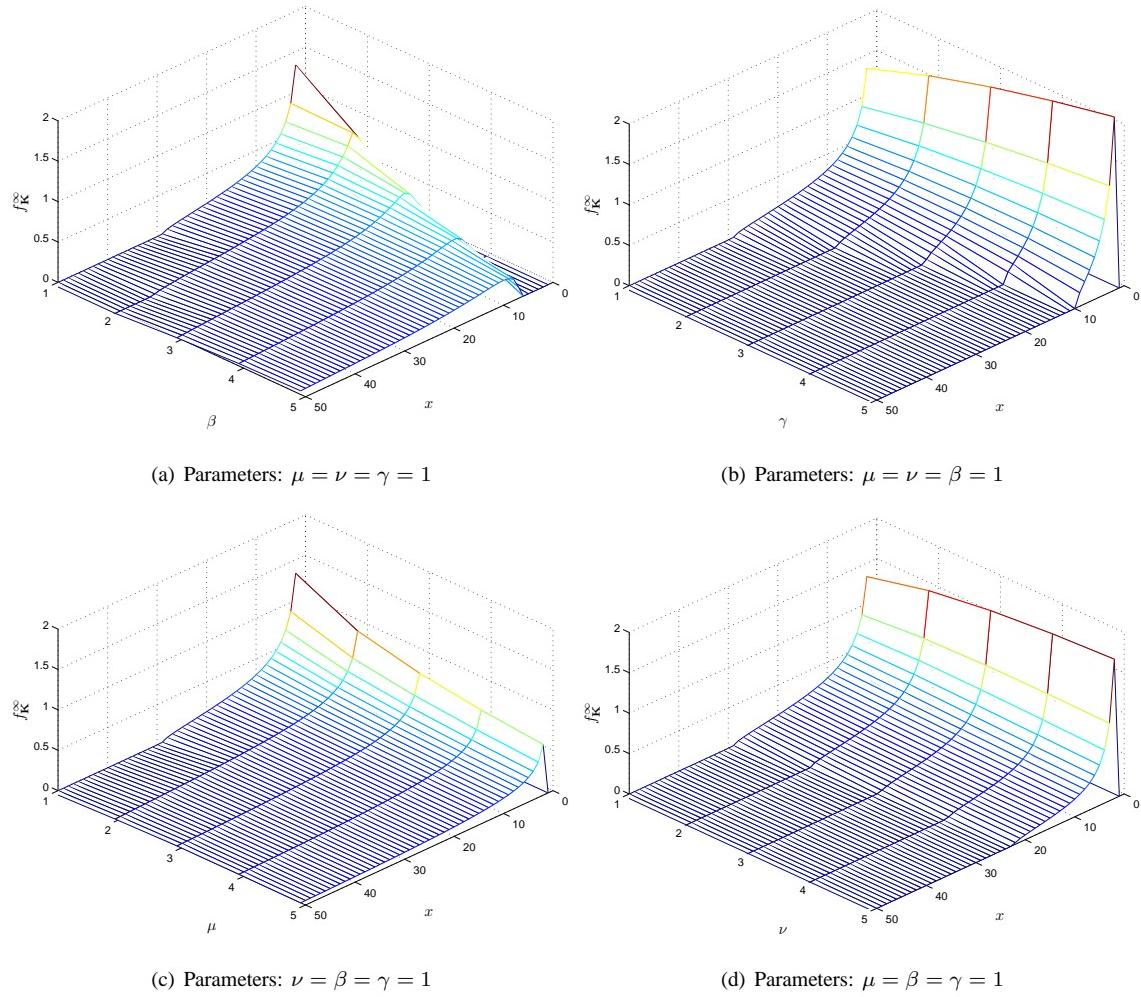


Fig. 2. The effect of transmit power ( $\mu, \nu$ ) and channel dimensions ( $\beta, \gamma$ ) on the a.e.p.d.f. of matrix  $\mathbf{K}$ .

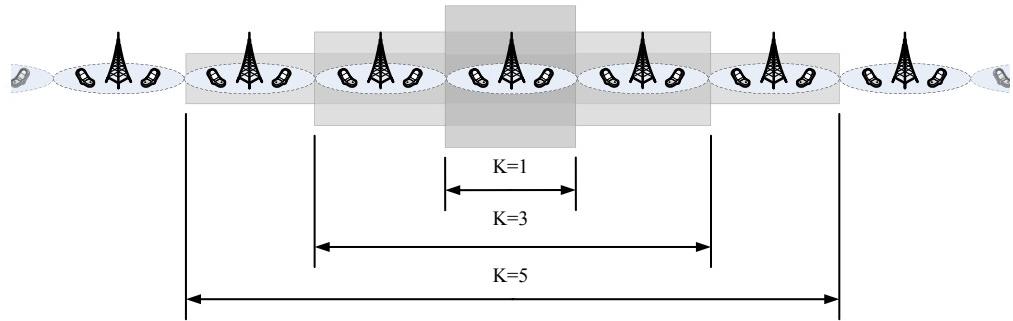


Fig. 3. Graphical representation of a linear cellular array with cooperating BS clusters.

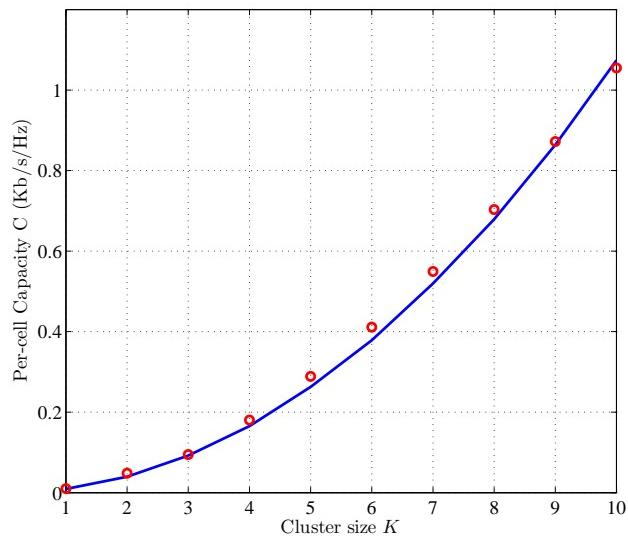


Fig. 4. Per-cell capacity scaling vs. the cluster size  $K$ .